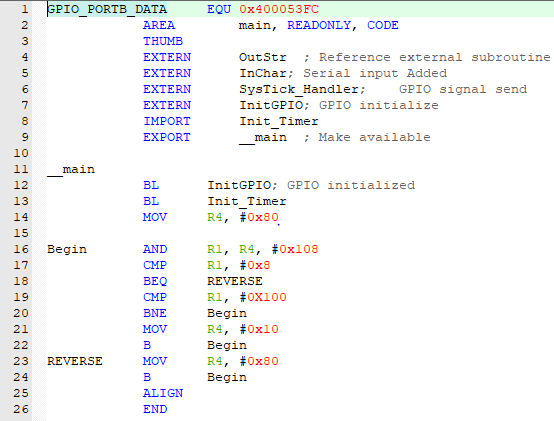
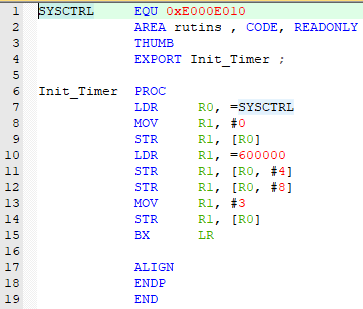
**EE447 EXPERIMENT #3**

**PRELIMINARY REPORT**

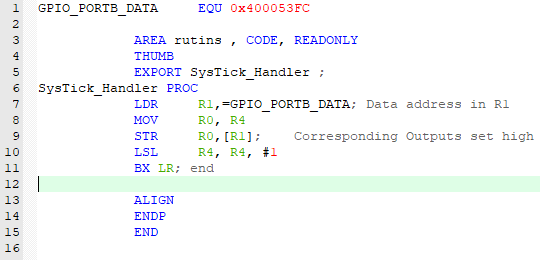
**Question 1-)** \_\_main.s



Init\_Timer.s

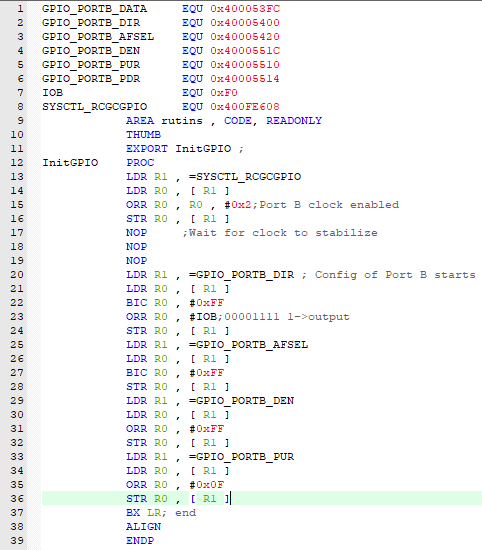


Signalsend.s

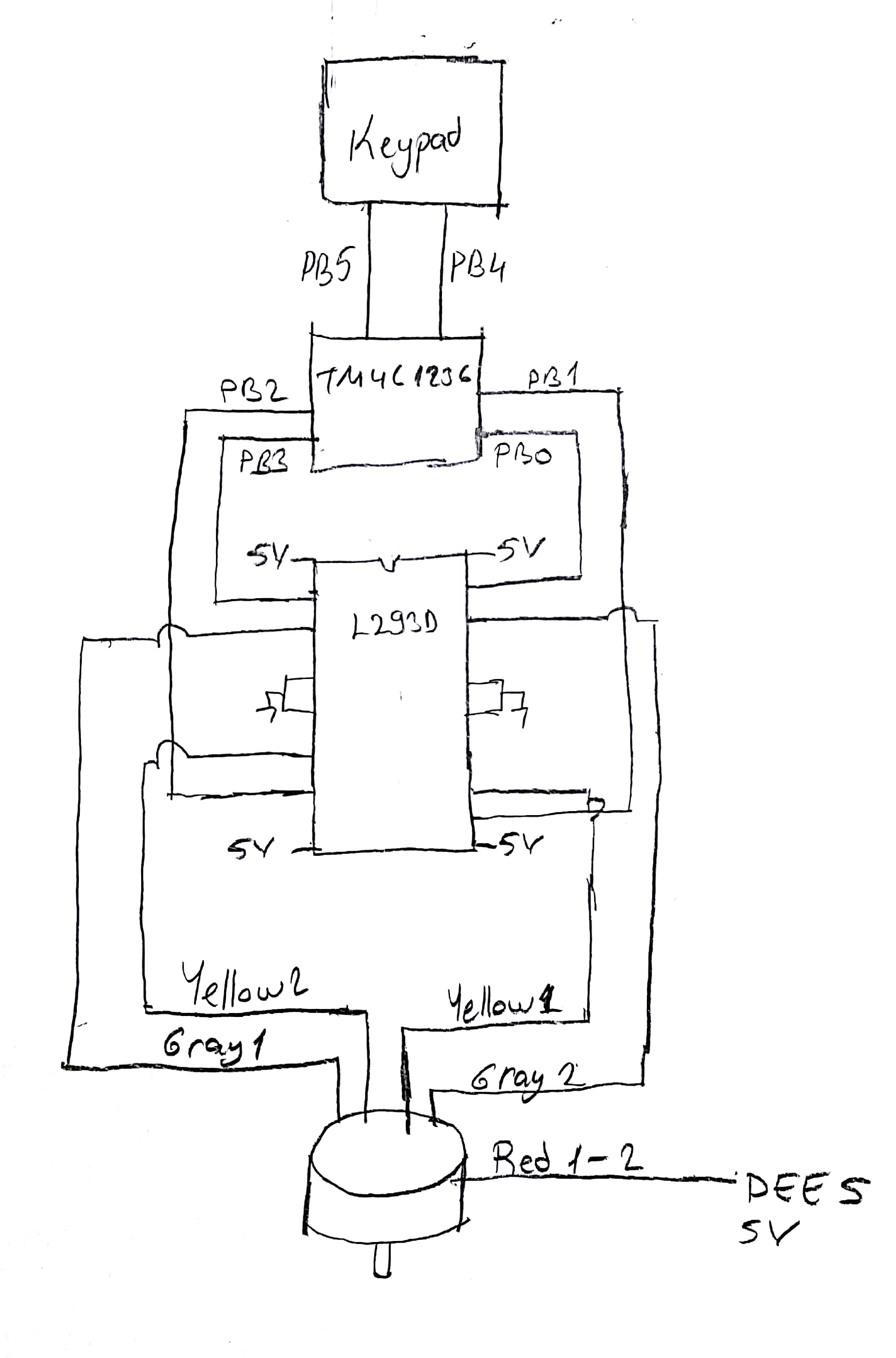


If we can change LSL with LSR, motor driving direction can be changed.

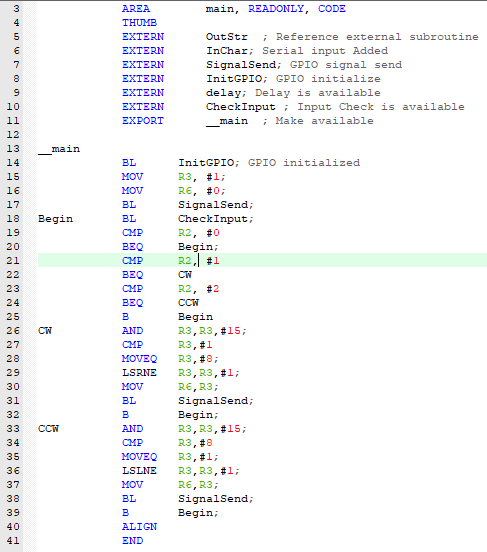
GPIO\_Init.s



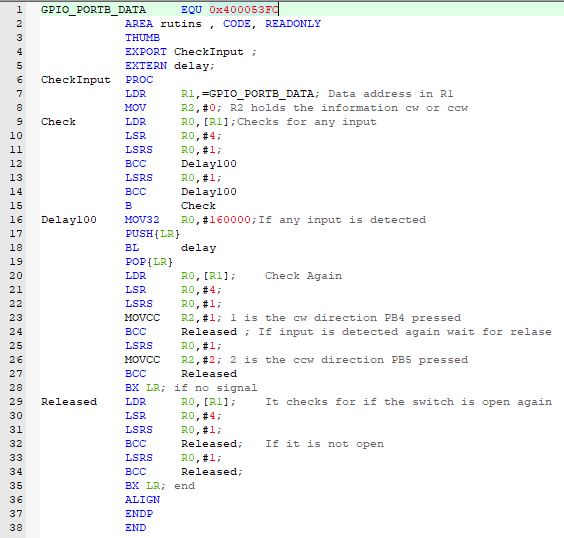
**Question 2-)**



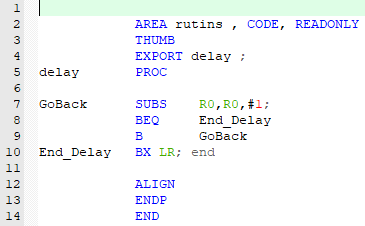
**Question 3-)** \_\_main.s



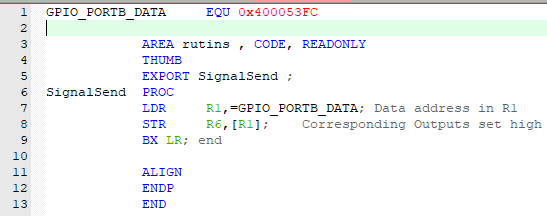
Inputcheck.s



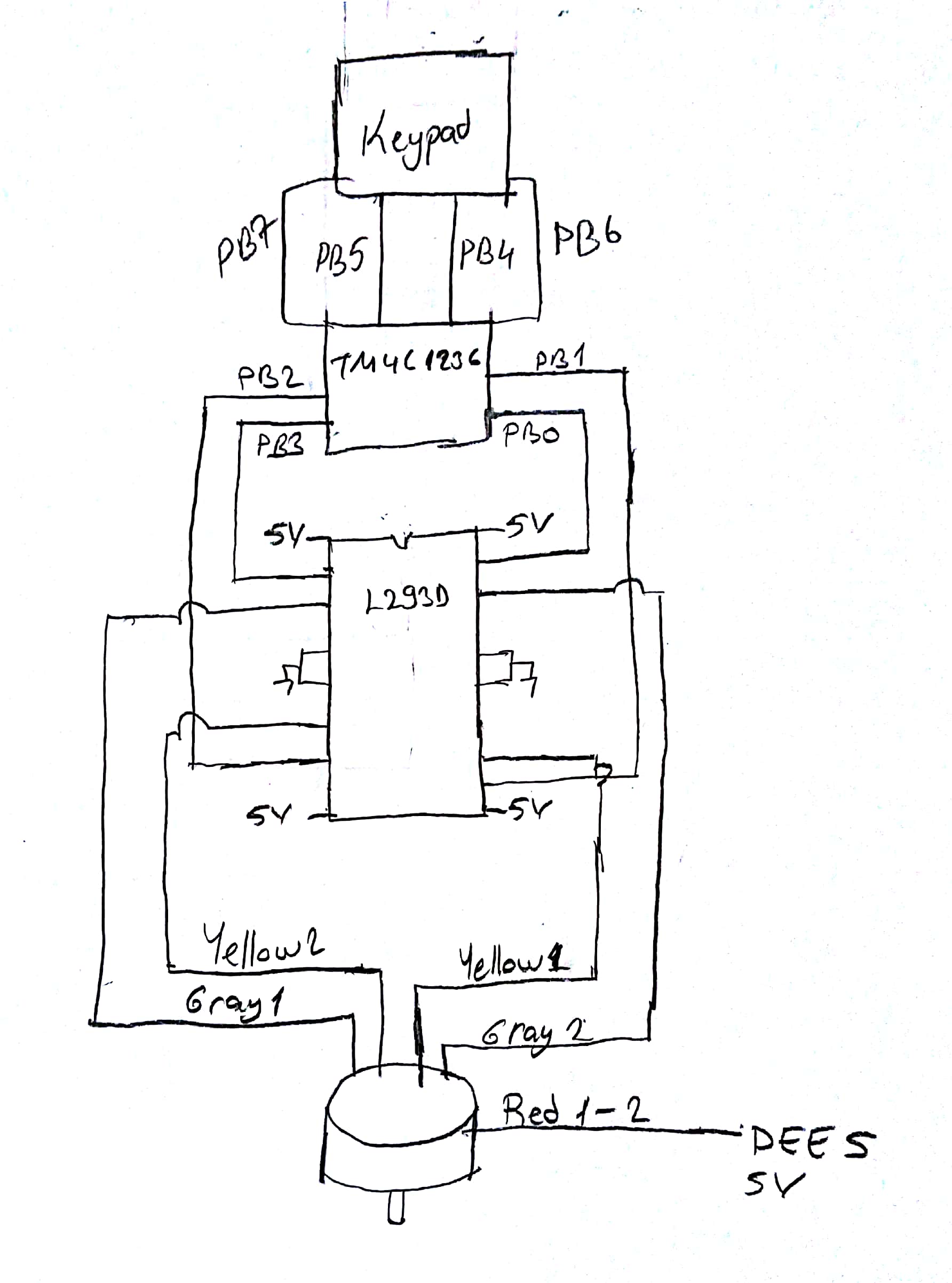
Delay.s



Signalsend.s

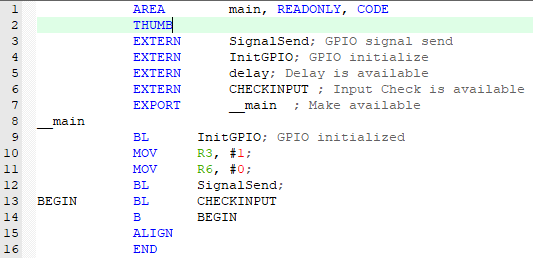


**Question 4-)**



**Question 5-)** In this problem, I specify some modes to determine which buttons are pressed. I write subroutines of 4 events. According to those modes, program runs the subroutine.

\_\_main.s



Checkinput.s

